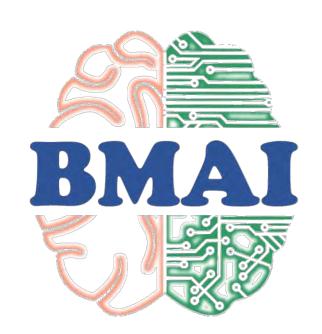
Brain-Morphic Al Ce-602, 604, 605, 606

Brain-Morphic Al to Resolve Social Issues

[Brain-Morphic AI]

Social Cooperation Programs, Institute of Industrial Science





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Social Cooperation Programs

https://www.iis.u-tokyo.ac.jp/en/research/department_center/social_ai/

Abstract

The purpose of this laboratory is to generate a novel type of computing systems including algorithms and devices, which can achieve very high performance of Al information processing with low power consumption like the brain to solve various social problems. For this sake, we develop novel fundamental technologies of the information processing based on mathematical analyses and neuromimetic circuit for the brain-morphic AI system which can execute fast intelligent-andautonomous information processing with low energy.

Schematics of Our Project

Problems of the conventional AI implementation

Especially for edge-side usage, we need low power consumption to solve social issues.

Our approach: Brain-Morphic Al

The Brain: Fast intelligent-and-autonomous information processing with low energy.

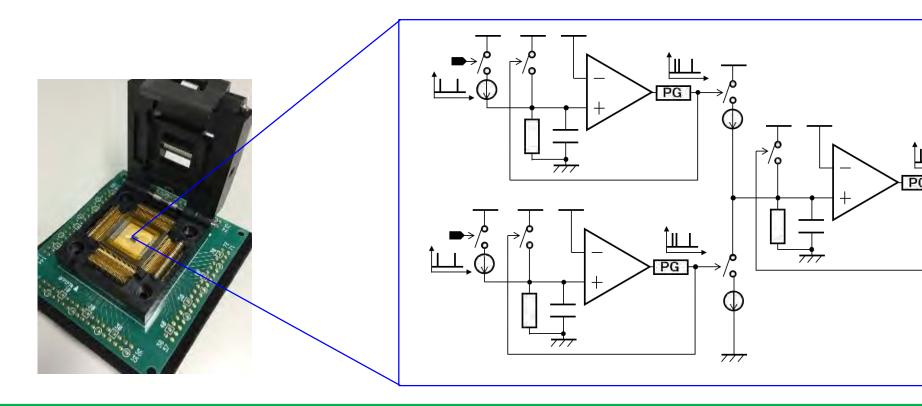


Brain-morphic circuits: implementation of Al information processing with low power consumption.

$$I = C_m \frac{dV_m}{dt} + g_k n^4 (V_m - V_K) + g_{Na} m^3 h (V_m - V_{Na}) + g_l (V_m - V_l)$$

$$\frac{dn}{dt} = \alpha_n (V_m) (1 - n) - \beta_n (V_m) n$$

$$\frac{dm}{dt} = \alpha_m (V_m) (1 - m) - \beta_m (V_m) m$$
 Cell body (The Hodgkin–Huxley model)



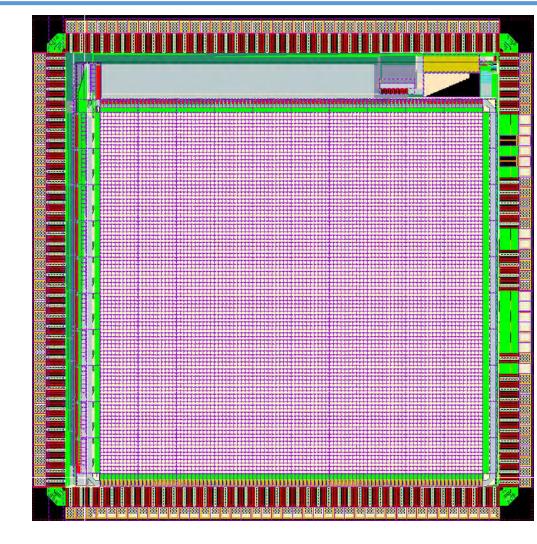
Novel fundamental technology of the information processing

- Very high performance of AI information processing with low power consumption.
- 2. Solve various social problems.

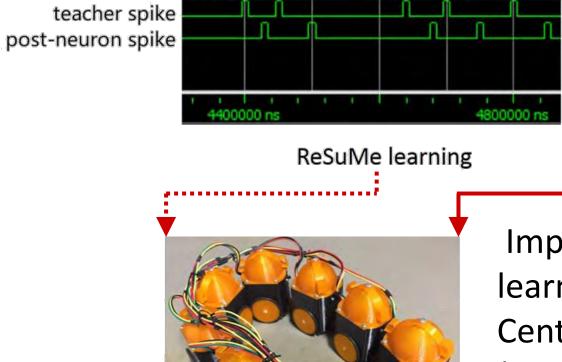
Recent Activities



A developed analog integrated circuit aiming at reproducing stochastic behavior of ion channels in real neurons and at generating pseudo-random numbers with low-power consumption.



Layout of an analog-digital mixed signal low power spiking neural network chip with on-chip learning.



Snake robot

Implementation in FPGA of ReSuMe learning (top Left), and biomimetic Central Pattern Generators (CPGs) (Top Right). The CPGs controls in realtime a snake robot (Bottom) and mimics the snake locomotion.

Biomimetic CPGs

ReSuMe: Remote supervised method (F. Ponulak, 2005)

