K. NAKANO LAB.

Safe and Comfort Mobility for Everyone



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Based on the fundamental fields of mechanics, vibration, and control engineering, researches on state monitoring, ergonomics, human-machine interface, automated driving, and cooperative systems related to mobility are conducted. Non-technical issues, called ELSI, are also being addressed, with the aim of implementing these technologies in society. The main research topics are as follows:

- 1. Research and Development of Human Machine Interface for Driver Initiated Take-over
- 2. Evaluation of Performance of Shared Control
- 3. Haptic Steering Assistance Based on Prediction of the Future Trajectory in Line with the Intention of the Driver
- 4. Fallback System of Automated Driving Vehicle Incorporating Potential Driver Intervention
- 5. Predicting Readiness and Performance of a Driver for Transitions from Automated to Manual Driving
- 6. Trajectory Prediction of Surrounding Vehicles Based on Traffic Scenario Understanding
- 7. Energy Harvesting in Rotating Body
- 8. Estimation of Condition Between Rail and Wheel from Measured Values of a PQ Wheel
- 9. Unified Traffic Control System for Railway and Road Vehicles Using Mobile Phone Line
- 10. Activities to Realize Level 4 Cooperated Automated Mobility Service
- 11. Building the Method for Social Implementation of Automated Driving Technology Complying with Actual State Based on ELSI













