

Han LAB.

Measurement, transmission & visualization of underwater info.

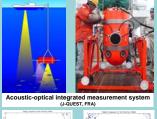
Underwater Technology Research Center

http://www.hanlab.iis.u-tokyo.ac.jp

Applied Underwater Information and Acoustic Measurement Systems

- · Applications of the acoustic video camera DIDSON in fisheries
- Underwater Acoustic communication and network System
- · Automated method for counting and sizing fish using a stereo camera
- visualization of hydrothermal activities and its volume measurement
 Automated method for counting and sizing fish using DIDSON

Automated 3D measurement method of in situ fish using two cameras



Control trapes

Control transcored monControl transc

Camera calibration

Binary image

Dilation and erosion

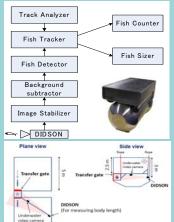
Tracing edges

Manage as polygon

Calculate area

Removing noises

Calculate centroid

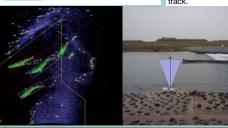


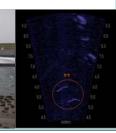


The background is subtracted from the image. Tracing the edges using a contour tracing method, the segmentation of the fish is obtained. To prevent recounting the same fish, a Kalman filter algorithm was designed and adapted to predict fish movements. Automated counting was performed by analyzing the spatiotemporal trajectory of the

epipolar line projective plan
epipole
Calculation of the center line of a fish

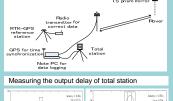




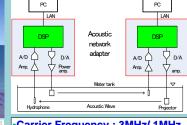


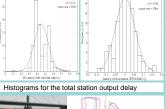
Development of a new total station synchronized with GPS

Short Range High Speed Underwater Acoustic Network System











*Carrier Frequency : 3MHz/ 1MHz
 *Modulation : BPSK
 *Bit Rate : 600k/200kbps
 *RX Bandwidth : 400k
 *A/D Converter : 16MHz

