Traffic Management and Control, Road Planning and Design, Automated Driving Systems





Cw504

Oguchi LAB.

[Technologies for Safe and Sustainable Traffic Society]

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Traffic Management and Control

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http://www.transport.iis.u-tokyo.ac.jp/en/

Scientific Approach for Traffic Flow

We research road traffic from various aspects and develop traffic management methods to realize sustainable road traffic with less traffic accident, congestion, and negative impact on environment.

Innovative policy

How to manage road traffic?

Studies on road management (incl. planning, design, operation) policies for more safe and efficient urban traffic flow:

Large-scale traffic simulation in the whole Tokyo Metro network at the Kashiwa ITS R&D field

Evaluation of the proposed systems

- Development of autonomous traffic signal systems
- Impact of traffic lights locations on driver's behavior
- Requirements for deploying automated driving systems
- Network control based on spatial congestion patterns
- Optimum crosswalk locations in urban street network
- Planning and design for hierarchical road network
- Promotion of open public transit data

Technology

How to assess road management policies?

Development of traffic simulation models and data complementing methods to assess road management policies:

- Operational evaluation system for three-ring expressways in the Tokyo Metro area
- Impact of shared automated driving systems on the use of urban parking lots
- Macroscopic model of urban rail systems
- Impact of random nature of shared left-turn lane
- Time series analysis of expressway OD traffic volume
- Traffic data imputation methods

ITS Intelligent Transport Svstems	$\frac{1}{1} = \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \frac{1}{1} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \frac{1}{1} \int_{\mathbb{R}^{2}} \int_{$	
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• Cont • Cont • Anal • Mod	inuum fluid model for motorway sag bottlenecks ysis of capacity drop at sag and tunnel bottleneck eling interactions among merging and mainline	<u>S</u>

vehicles at expressway on-ramps

• Left-turn trajectory estimation using jerk minimization principle



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