**CSGI** 

## KAMIJO Lab

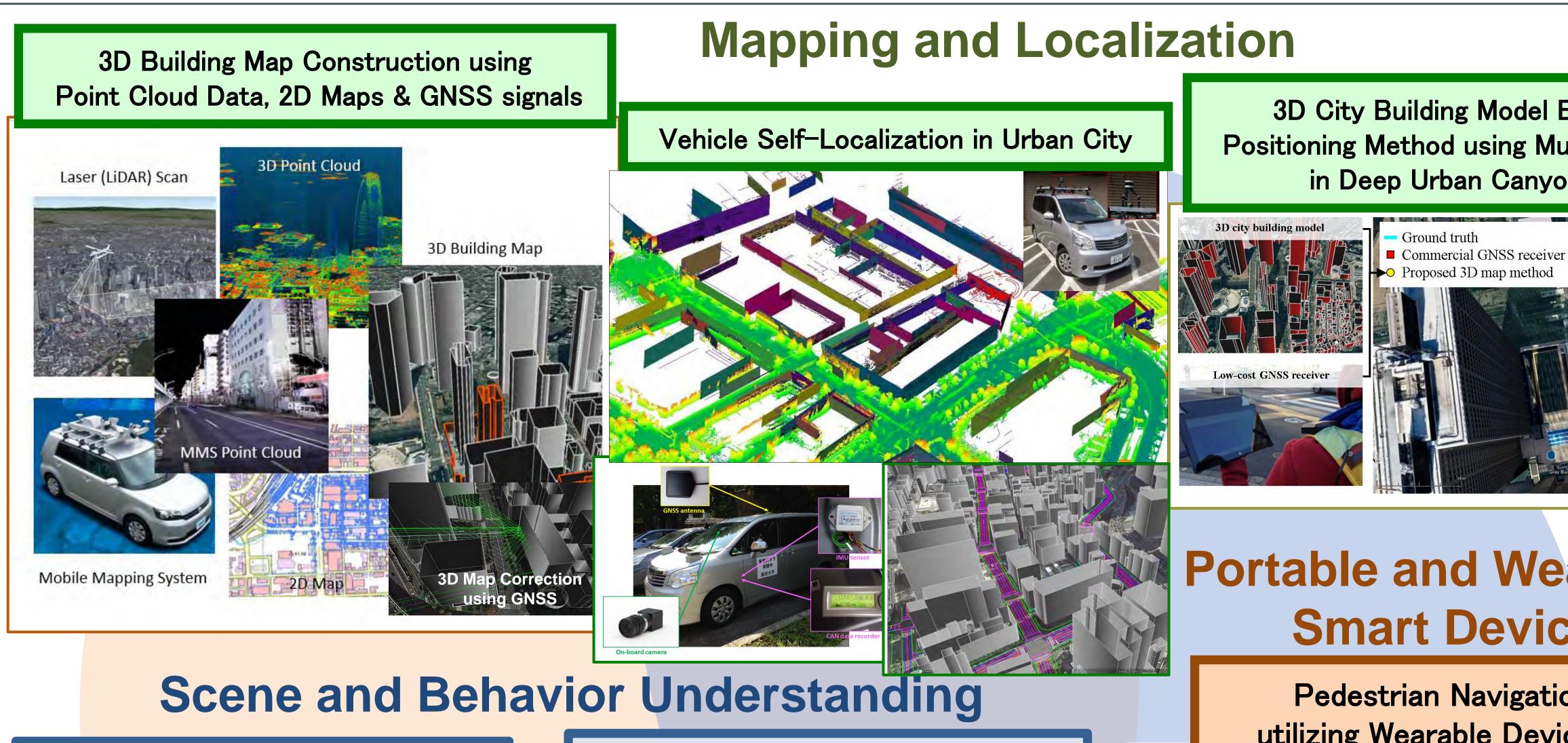
## [Integrated Research of Location Service]

Center for Socio-Global Informatics

Applied Multimedia Information Processing

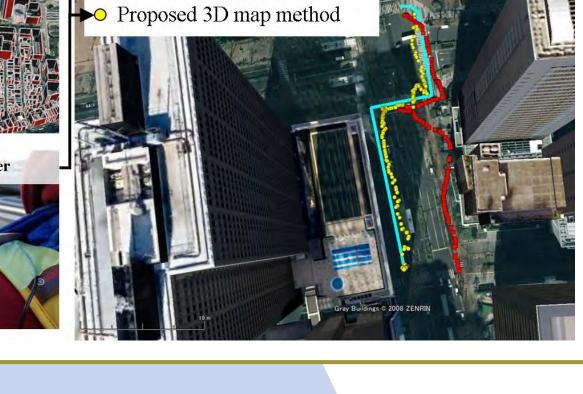
Information and Communication Engineering/Emerging design and informatics course

http://kmj.iis.u-tokyo.ac.jp



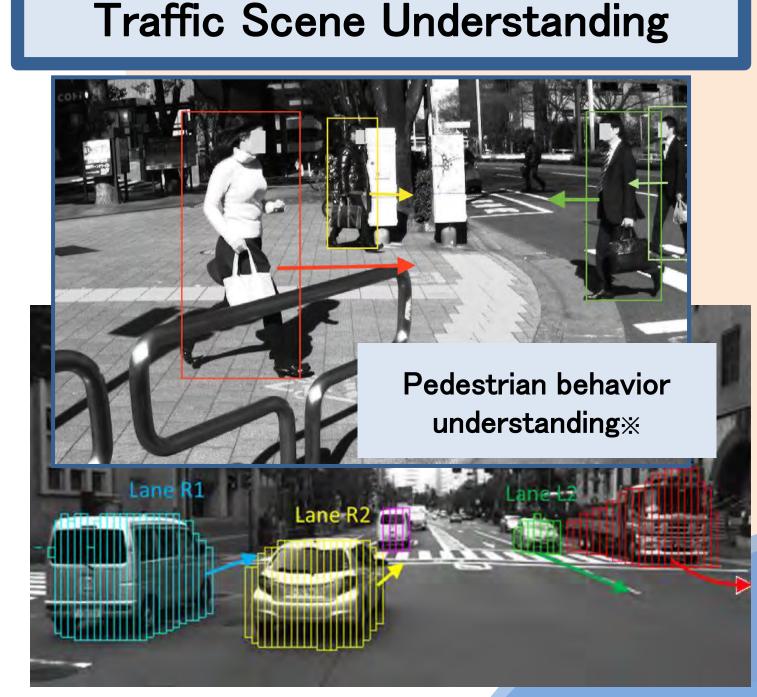
3D City Building Model Based

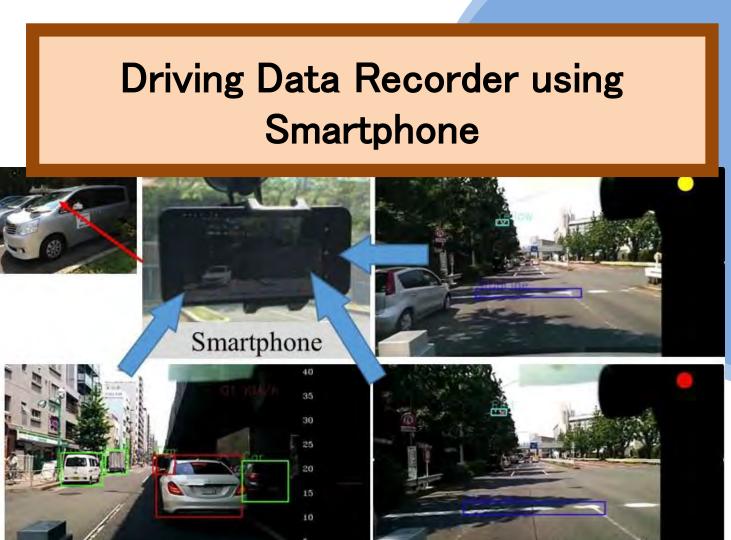
Positioning Method using Multi-GNSS in Deep Urban Canyons



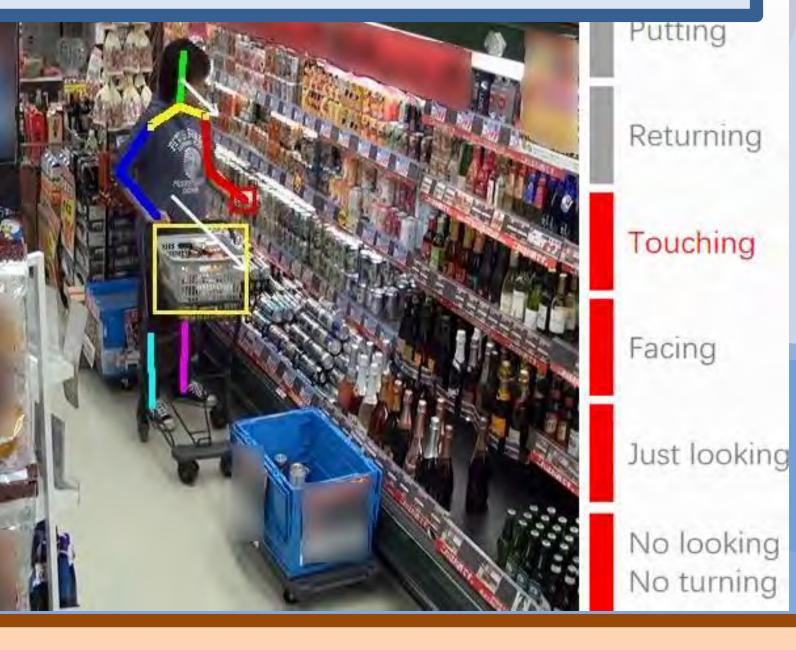
## Portable and Wearable **Smart Device**

Pedestrian Navigation utilizing Wearable Devices\*





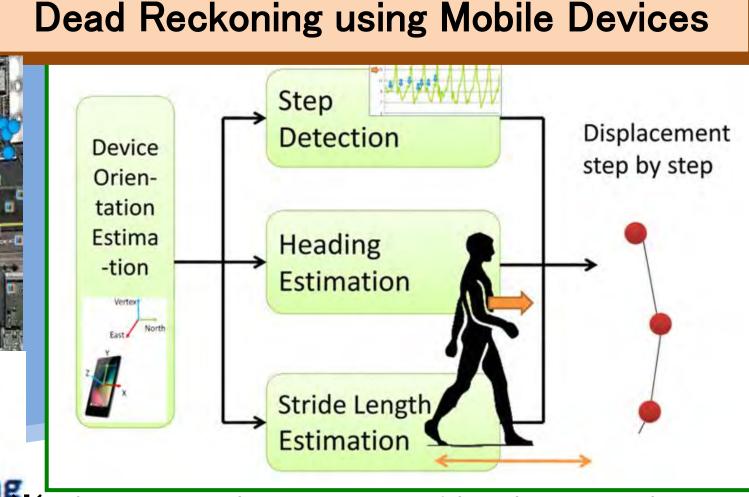




**Customer Behavior Recognition** 

Lifelog using Mobility Context Information in Mobile Devices

Localization and GNSS receiver Navigation Gyroscope, 3D city Accelerometer, Magnetometer model Vision Sensor → Observation from smart glasses



Location Estimation and Pedestrian

Walking Running. This research is permitted by the Compliance Committee of The University of Tokyo

The safety of people and vehicles • The realization of social security

In recent years, autonomous driving and Advanced Driving Assistant Systems (ADAS) attract lots of attention. We are developing Self-localization, Scene Understanding and 3D MAP technology, which are essential to autonomous driving and ADAS. In this way, we are intend to meet the social request that ensuring the safety of people and vehicles.



map matching