While attention on automated driving of automobiles increases, aiming for augmentation of a driver, human oriented mobility engineering researches such as shared control, human-machine interface, and high level sensing have been conducted. The followings are topics of our researches.

1. Research and Development of Human Machine Interface for Driver Initiated Take-over
2. Evaluation of Performance of Shared Control
3. Driver Model for Shared Control
4. Steering Control Using sEMG
5. Effect of In-Vehicle Traffic Signal on Driving Behavior
6. Steering Controller Design of Automated Driving Bus
7. Dynamic Driving Task Fallback System for an Automated Vehicle Encountering Sensor Failure in Monitoring Driving Environment
8. Energy Harvesting in Rotating Body
9. Decreased Deceleration Detection of Railway Vehicle in Snow Condition
10. Estimation of Condition Between Rail and Wheel from Measured Values of a PQ Wheel
11. Unified Traffic Control System for Railway and Road Vehicles Using Mobile Phone Line
12. Building the Method for Social Implementation of Automated Driving Technology Complying with Actual State Based on ELSI

http://www.knakanolab.iis.u-tokyo.ac.jp/english/index_en.htm